WINGLETS – MULTIOBJECTIVE OPTIMIZATION OF AERODYNAMIC SHAPES

SOHAIL R. REDDY¹, HELMUT SOBIECZKY², ABAS ABDOLI¹ AND GEORGE S. DULIKRAVICH^{1*}

¹ Department of Mechanical and Materials Engineering, MAIDROC Laboratory, Florida International University, Miami, FL 33174, USA {sredd001@fiu.edu, <u>aabdo004@fiu.edu</u>, dulikrav@fiu.edu} <u>http://MAIDROC.fiu.edu</u>

² University of Technology, Institute of Fluid Mechanics and Heat Transfer, Vienna, Austria E-mail: helmut@sobieczky.at Http://www.sobieczky.at/aero/

Key Words: Winglets, Aerodynamic Shape Design, Multi-Objective Optimization

Abstract. Various configurations for airplane wing tip winglets have been investigated by performing 3D aerodynamic analysis. An existing blended winglet has been equipped with a secondary lower element to create a split winglet configuration. At winglet tips, a trailing edge extension was added to create scimitar streamwise spikes. A total of eight variables were used to define the winglet geometry. The presented design methodology utilizes a second order continuous, 3D geometry generation algorithm based on locally analytical surface patches. This algorithm requires a minimal number of design parameters to be varied in order to create vastly different 3D geometries of the winglets attached to a clean wing which is blended with the fuselage. A 3D, compressible, turbulent flow analysis was performed using a Navier-Stokes solver on each configuration to obtain objective function values. Each configuration was analyzed at free stream Mach number of 0.25 and an angle of attack of 11 degrees to mimic takeoff conditions of a passenger aircraft. Multi-objective optimization was carried out using modeFRONTIER utilizing a radial basis function response surface approximation coupled with a genetic algorithm. Maximizing coefficient of lift and lift-todrag ratio, while minimizing coefficients of drag and magnitude of coefficient of moment, were the four simultaneous objectives. Performance benefits of individual components of the optimized geometry were also investigated.

The split-scimitar winglets feature a traditional blended winglet design retrofitted with a secondary lower ventral strake (Figure 1). Both the blended winglet and the ventral strake are caped with a blended-sweptback tip spike. The effects of each of these individual components were investigated in this work. A multi-objective optimization was carried out to find a design satisfying the four simultaneous objectives: minimize coefficient of drag and the magnitude of the coefficient of moment, and maximizing the coefficient of lift and lift-to-drag ratio.

From Table 1 it is clear that optimized scimitar split-winglets with streamwise tip spikes offer significant increase of lift and lift-to-drag ratio, while simultaneously lowering aerodynamic drag and significantly lowering aerodynamic moment.

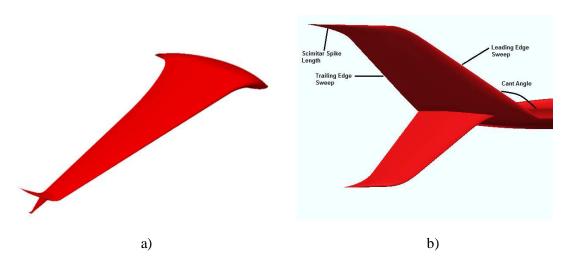


Figure 1: A Boeing 7E7 wing with a scimitar winglet (a) and some of the geometric design parameters for scimitar winglet (b).

		ΔC_{L}		ΔCD		ΔC_m		$\Delta(C_L/$
Configurations		%		%		%	C _L /	C _D
Evaluated	CL		CD		Cm		CD	%
Naked Boeing		0		0		0		0
7E7 wing without								
winglets	0.6510		0.1310		-0.121		4.97	
Pareto optimized		3.41		-4.43		-22.97		8.25
standard blended								
winglet	0.6732		0.1252		-0.0932		5.38	
An initial (non-		3.68		-5.34		-14.87		9.45
optimized) split								
winglet								
configuration	0.6750		0.1240		-0.103		5.44	
Pareto optimized		6.23		-5.73		-28.10		11.23
split winglet								
without tip spikes	0.6916		0.1239		-0.0870		5.58	
Pareto 2996 case		6.54		-7.02		-31.40		14.48
optimized split								
winglet with tip								
spikes	0.6936		0.1218		-0.0830		5.69	

Table 1: Objective fun		•			C *
Table I. () bioctive tun	otion values and	narcantaga improvem	ante tor varioue	WING WINGLA	continuratione
	CUICH VALUES AND		EILS IOF VALIOUS	w m r r w m r r r	CONTINUATIONS
		F			

REFERENCES

- M. Klein and H. Sobieczky. Sensitivity of aerodynamic optimization to parameterized target functions. In: M. Tanaka, G.S. Dulikravich, (eds.), *Inverse Problems in Engineering Mechanics*, Elsevier Science, UK, 2001.
- [2] R.J. Moral and G.S. Dulikravich. Multi-objective hybrid evolutionary optimization with automatic switching among constituent algorithms. *AIAA Journal*, Vol. 46, No. 3, March 2008, pp. 673-700.