

## Programming shape-morphing of dielectric elastomers through Multifunctional Topology Optimization

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This paper presents a topology optimization framework for the design of shape-morphing dielectric elastomers (DE) undergoing complex electrically induced deformations. Two different mechanisms are explored to induce Gaussian curvature changes. The first one aims at creating an inhomogeneous electric field inside the DE through the careful design of spatially varying internal electrode meso-architecture, yielding inhomogeneous actuation modes. The second one explores the use of TO techniques with the aim of designing a spatially varying distribution of stiffeners, namely, passive material devoid from electro-mechanical properties, yielding an anisotropic response of the material. A series of proof-of-concept examples (in both circular and squared geometries) are presented in order to demonstrate the robustness of the methodology and its potential as a new tool for the design of new DE-inspired soft robotics components. The ultimate objective is to help thrive the development of this technology through the in-silico production of voltage-tunable (negative and positive Gaussian curvature) DEs shapes beyond those obtained solely via trial-and-error experimental investigation.

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