

ADAPTIVE C^0 INTERIOR PENALTY METHOD FOR BIHARMONIC EIGENVALUE PROBLEMS

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This talk presents a residual based *a posteriori* error estimator for biharmonic eigenvalue problems and the C^0 interior penalty method. Biharmonic eigenvalue problems occur in the analysis of vibrations and buckling of plates. The *a posteriori* error estimator is proven to be reliable and efficient for sufficiently large penalty parameter $\sigma \geq 1$ and sufficiently small global mesh size H . The theoretical results are verified in numerical experiments.

The C^0 interior penalty method [1, 3] avoids the use of complicated C^1 finite elements but uses standard Lagrange finite elements of total degree $k \geq 2$ for some triangulation \mathcal{T}_ℓ . This method is nonconforming in the sense that $P_k(\mathcal{T}_\ell) \cap H_0^1(\Omega) := V_\ell \not\subset H_0^1(\Omega)$, and the associated nonconforming bilinear form is symmetric, continuous and coercive for sufficiently large penalty parameter $\sigma \geq 1$ [1, 3]. Similar to the *a posteriori* error estimator for the source problem [2], the *a posteriori* error estimator η_ℓ for the vibrating plate, with discrete eigenpair $(\lambda_\ell, u_\ell) \in \mathbb{R}_+ \times V_\ell$, set of edges \mathcal{E}_ℓ , set of interior edges \mathcal{E}_ℓ^i , jump $[[\cdot]] = \cdot|_{T_+} - \cdot|_{T_-}$ across an edge $E = T_+ \cap T_-$, $T_\pm \in \mathcal{T}_\ell$, and polynomial degree $k = 2$, reads

$$\eta_\ell^2 := \sum_{T \in \mathcal{T}_\ell} h_T^4 \lambda_\ell \|u_\ell\|_{L_2(T)}^2 + \sum_{E \in \mathcal{E}_\ell} \frac{\sigma^2}{h_E} \|[[\partial u_\ell / \partial n]]\|_{L_2(E)}^2 + \sum_{E \in \mathcal{E}_\ell^i} h_E \|[[\partial^2 u_\ell / \partial n^2]]\|_{L_2(E)}^2.$$

The *a posteriori* error estimator η_ℓ is proven to be reliable and efficient up to higher order terms in some mesh-dependent norm. The reliability and efficiency of η_ℓ^2 for the eigenvalue error $|\lambda - \lambda_\ell|$ is verified in numerical experiments with varying penalty parameters, sizes of eigenvalues, and for convex and non-convex domains.

REFERENCES

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