

Simulations of Advanced Signal Processing Techniques for Remote Sensing

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Outline

- Simulation Tools
- (Not So Hard)ware
- Example 1: Correlation Function
- Example 2: Sideband Splitting
- Example 3: Phase-Locked Loops
- Summary

Simulation Tools Already Exist

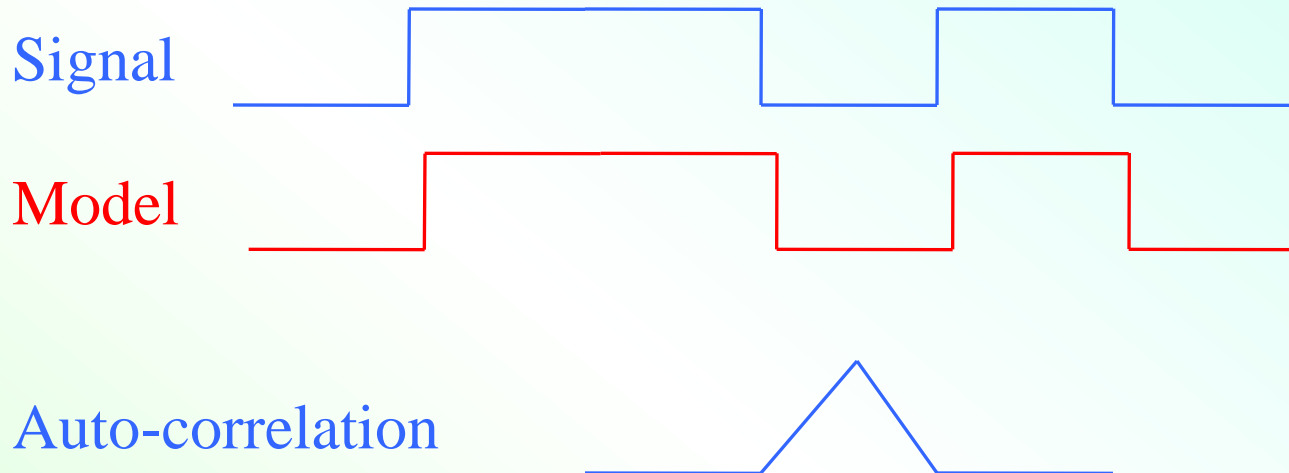
- Ocean Surface Scattering Monte Carlo
 - Elfouhaily wave spectrum
 - Sub-meter integration cells on surface
 - Spacecraft-altitude receiver
 - Optimized for multi-node processing (but no MPI)
 - Recently added polarization
- Software receiver
 - Easy to implement new processing algorithms
 - Test concepts on real data

Modern (Not So Hard)ware

- Many receiver functions are now reconfigurable
 - Especially true for flight receivers
 - Non-standard processing possible
 - Receiver modifications “just” a software upload
- ⇒ Time is right to search for creative new processing schemes
- Three Examples
 - Modified correlation function
 - Bandpass filtering
 - Phase-locked loops

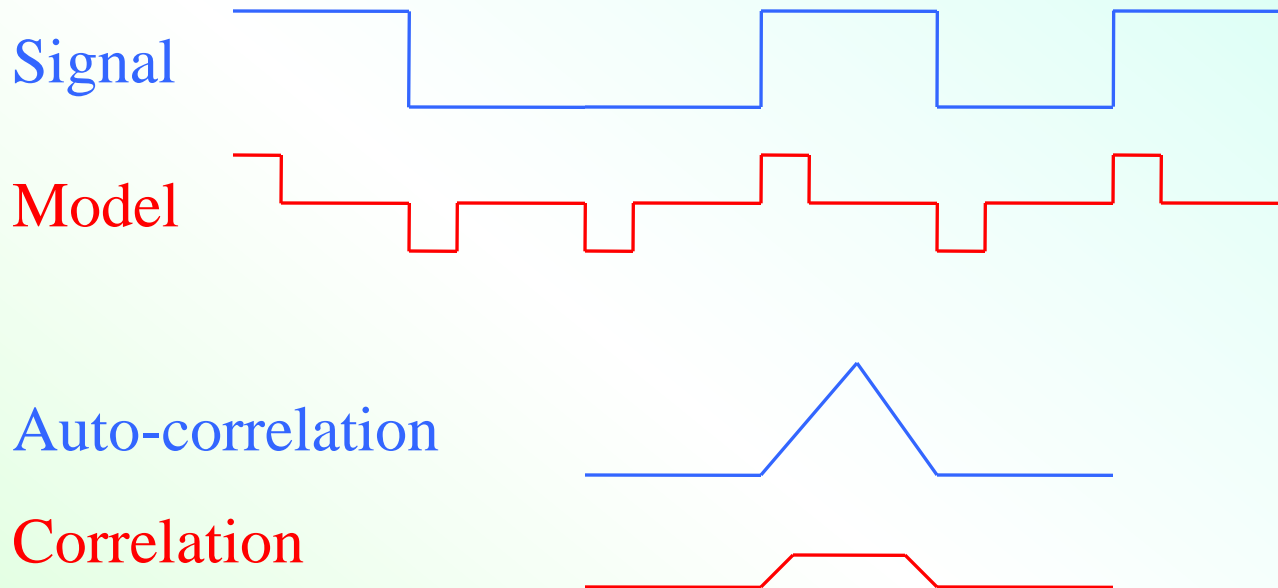
Example 1: Modified correlation function

- Model is usually a close replica of the signal

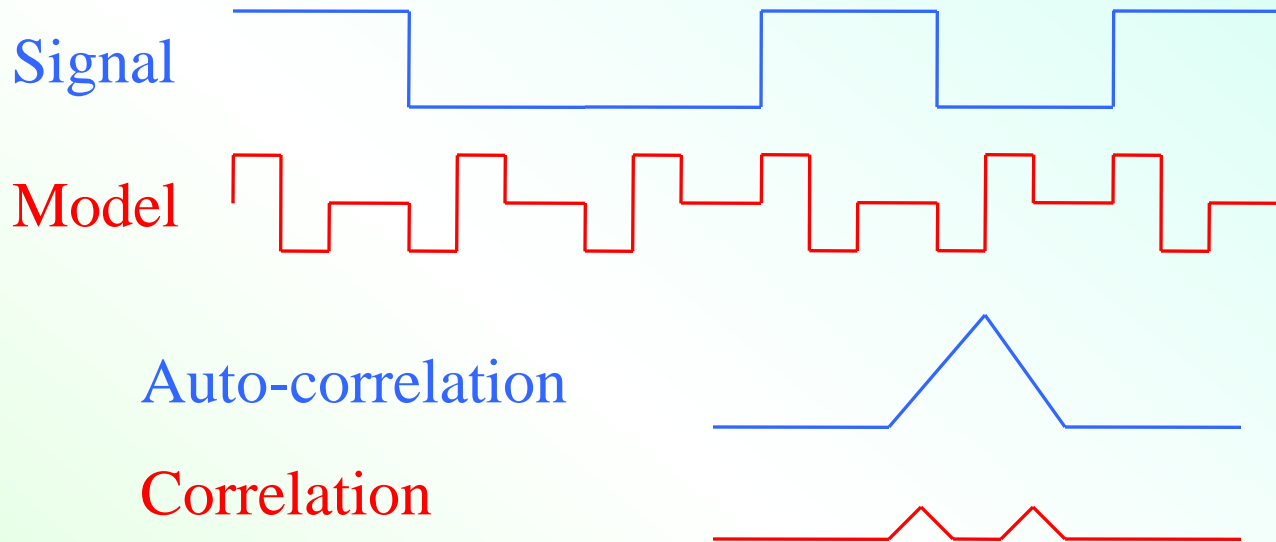


Example 1: Modified correlation function

- Correlation functions can blank, or negate signal

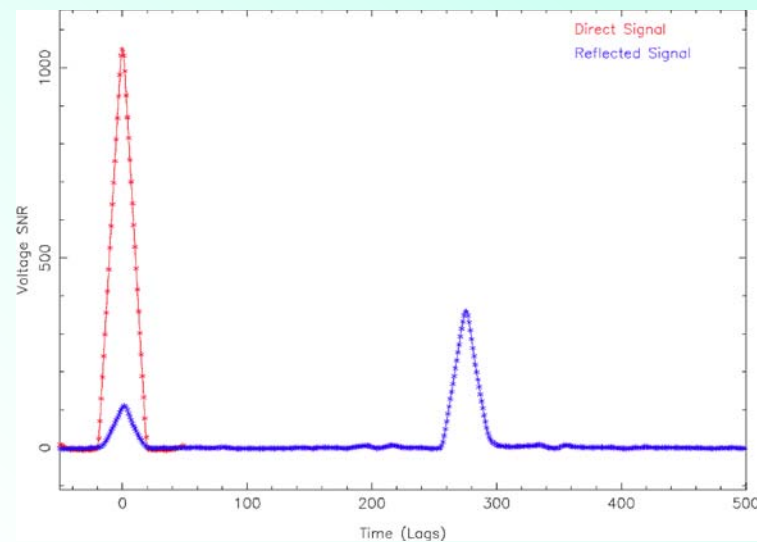


Delta-dot Chipping Function



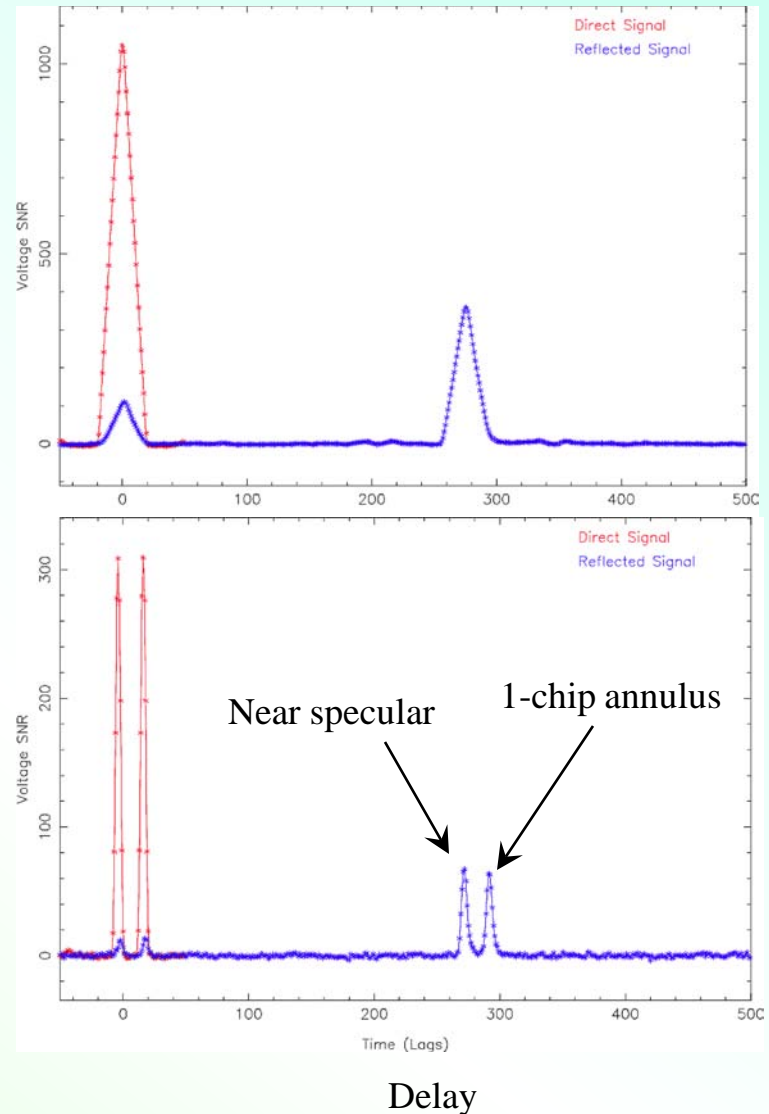
- Novel correlation functions, but lower SNR
- Must account for finite bandpass

- Aircraft data over ocean
- GPS C/A code
- Standard processing



- Aircraft data over ocean
- GPS C/A code
- Standard processing

- Non-standard correlation function
- Narrower correlation function
But lower SNR (don't win)
- Smaller surface footprint
 - Better spatial resolution
 - Coherence may be better
 - Differences between peaks



Example 2: Sideband splitting

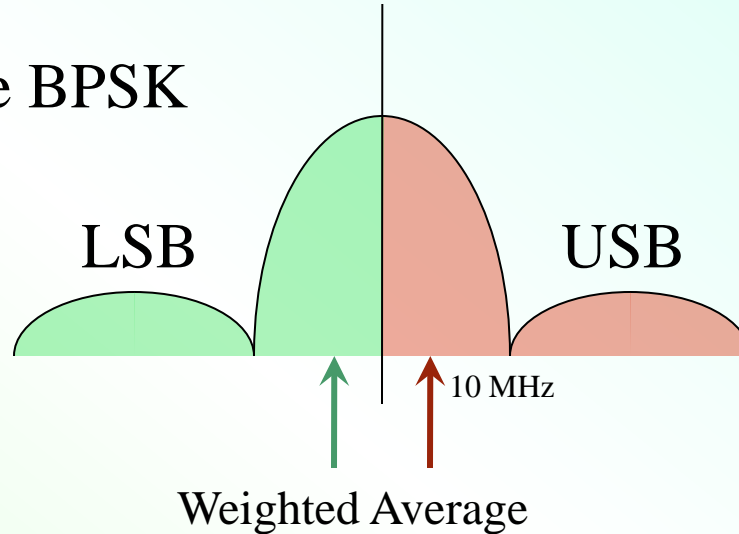
- Filter model into upper/lower sidebands
- Correlate each with unfiltered data
- Resulting waveforms at 2 different frequencies

$$\Rightarrow \text{Phase Delay} = \Delta\phi / \Delta\nu$$

- Precision same as fitting to model waveform
- No model waveform needed

Example 2: Sideband splitting

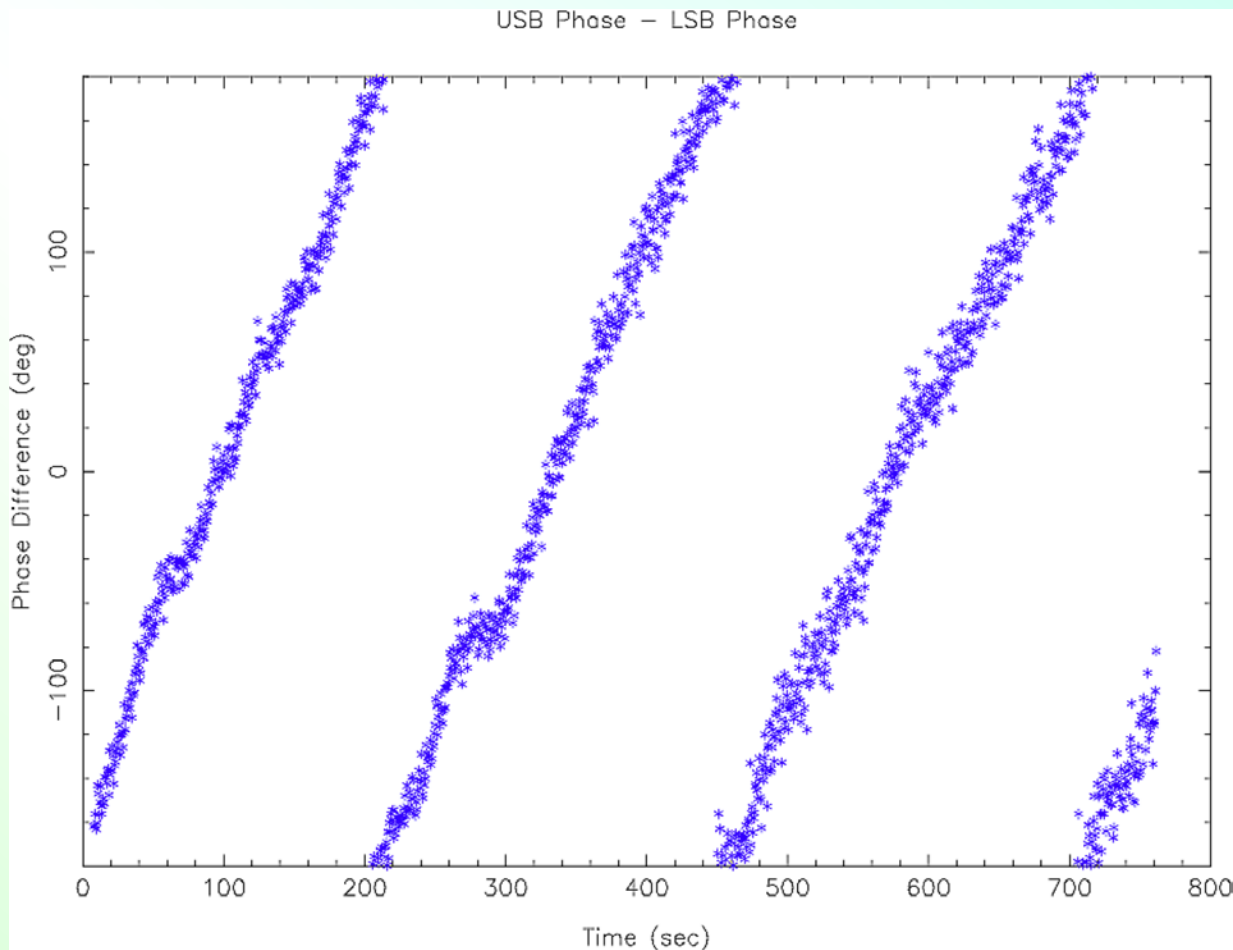
GPS P(Y) code BPSK



- BOC signals better
 - Power at bandpass edges

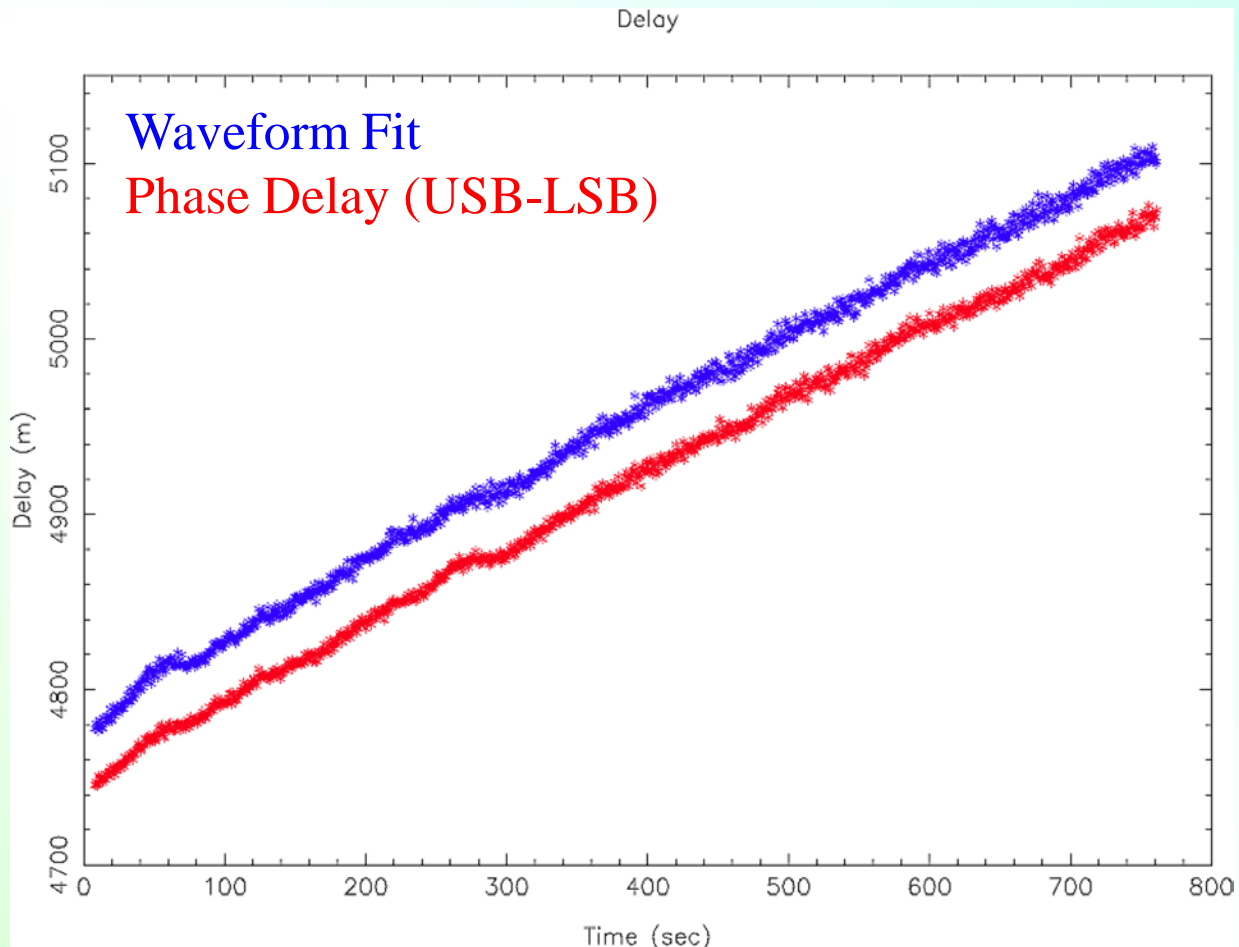
Example 2: Sideband splitting

Aircraft data



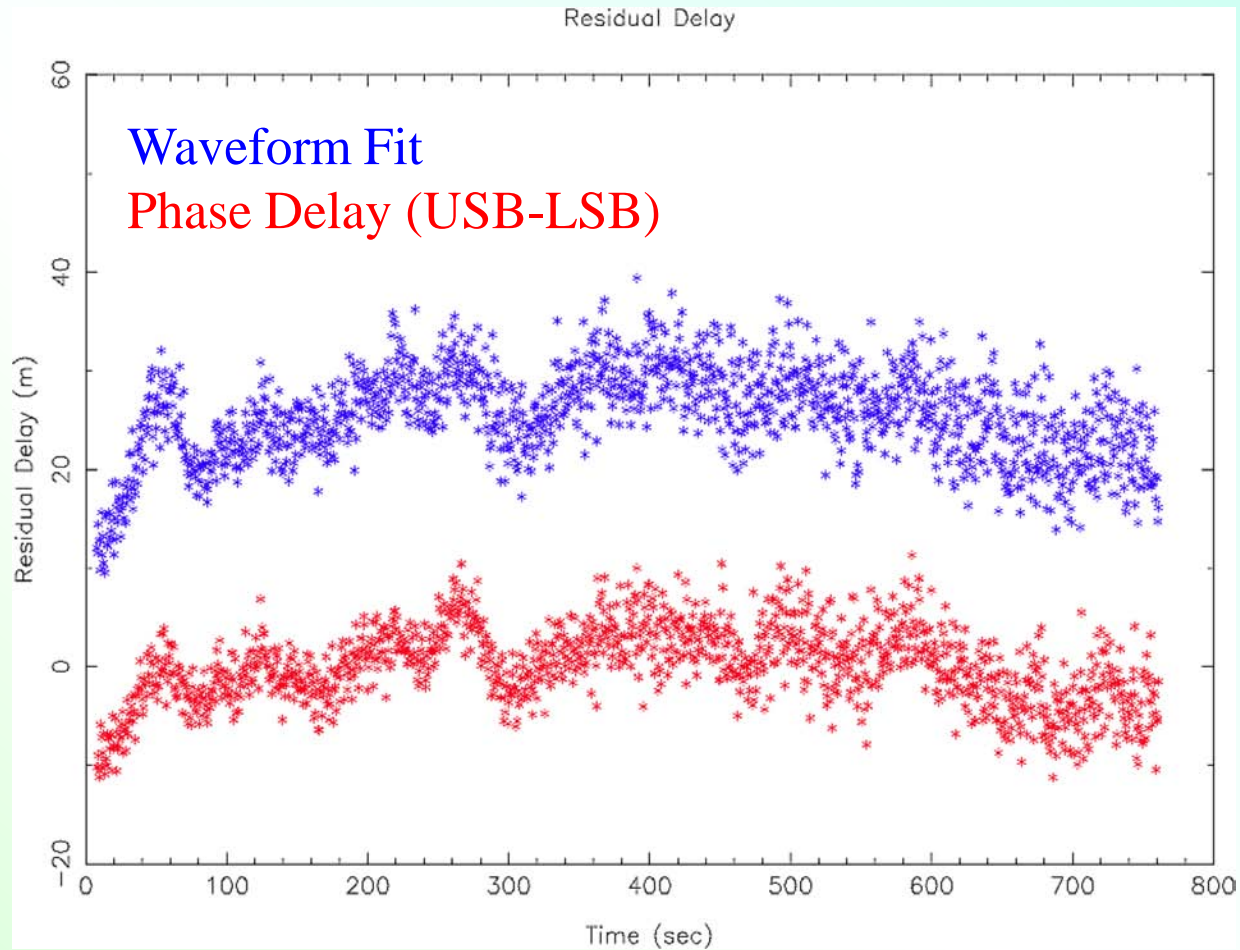
Example 2: Sideband splitting

Aircraft data



Example 2: Sideband splitting

Aircraft data



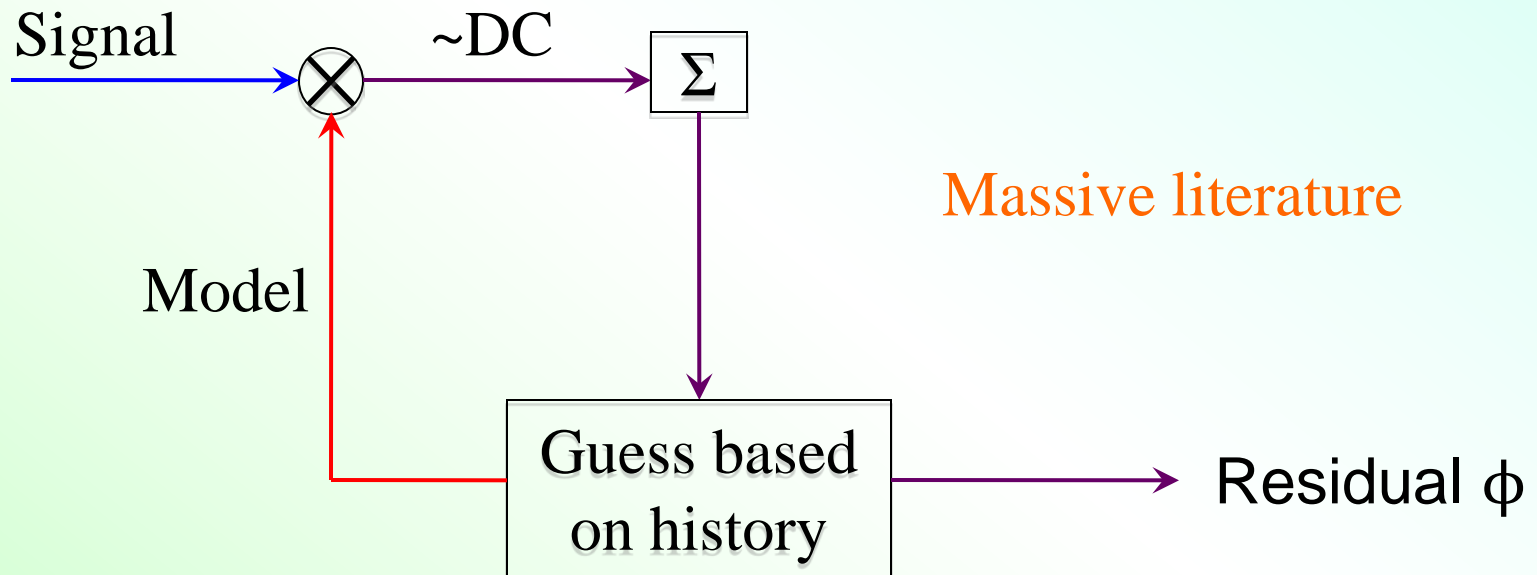
Example 2: Sideband splitting

- Phase-Delay observable is available
- No precision improvement over waveform fitting, but:
 - May be easier to process onboard
 - May have better accuracy (?)
 - BOC signals have power on bandpass edges

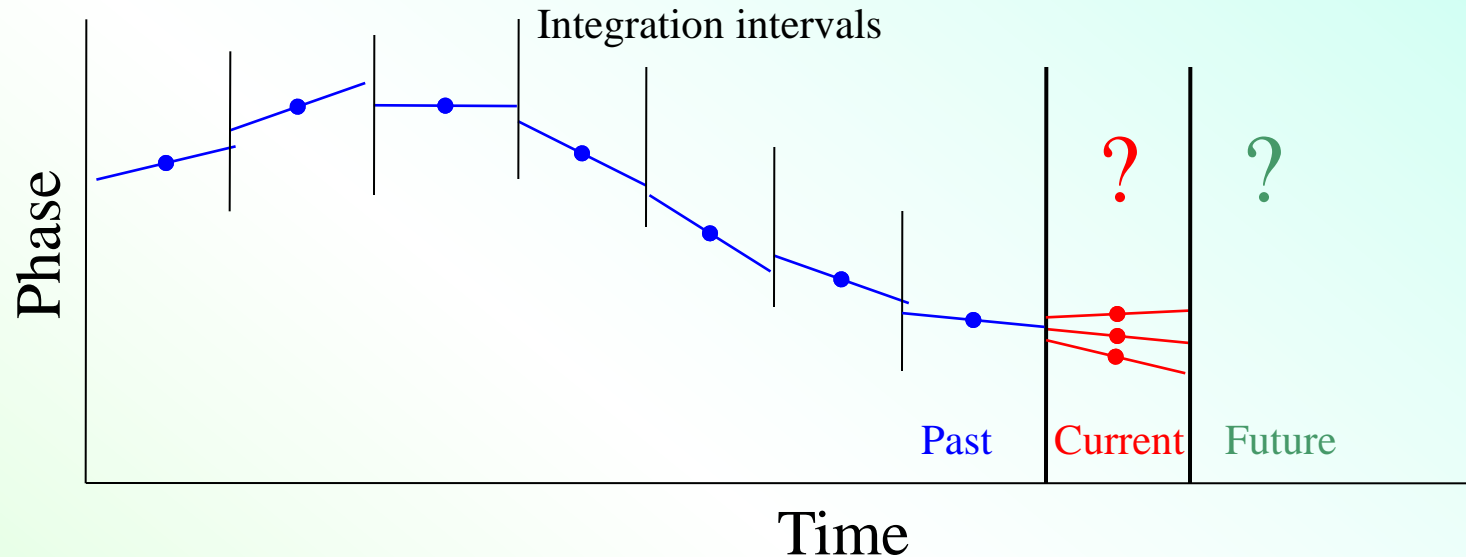
Example 3: Phase-Locked Loops

What are PPLs really? (in tracking loops)

⇒ Efficient guess at model phase based on past signal history



Example 3: Phase-Locked Loops



Assumptions

- Signal low-frequency peaked
- Stable signal amplitude
- Initiated with “acquisition”

Example 3: Phase-Locked Loops

PPL Properties

- One guess
 - A bad guess or two \Rightarrow loose lock, tracking stops
- Asymmetric in time
- Locally stable, globally unstable

Example 3: Phase-Locked Loops

PPL Properties

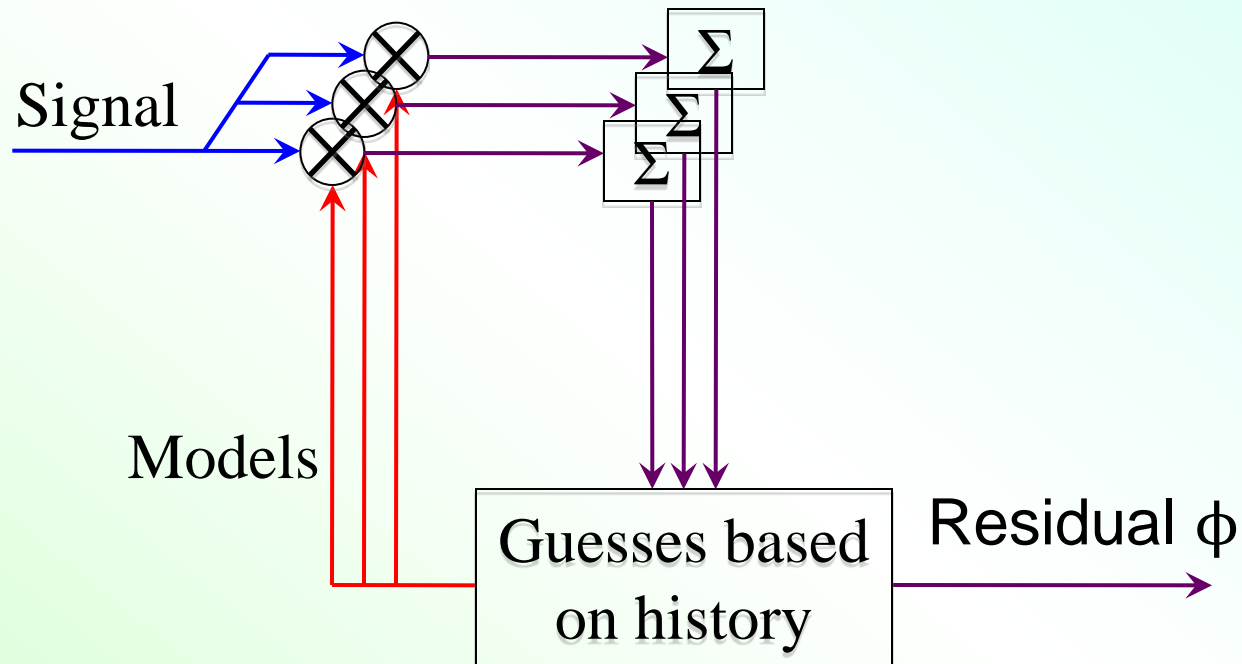
- One guess
 - A bad guess or two \Rightarrow loose lock, tracking stops
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What if acquisition is permanent!

- No PLL
- No loss of lock (no lock)
- Requires lots of hardware

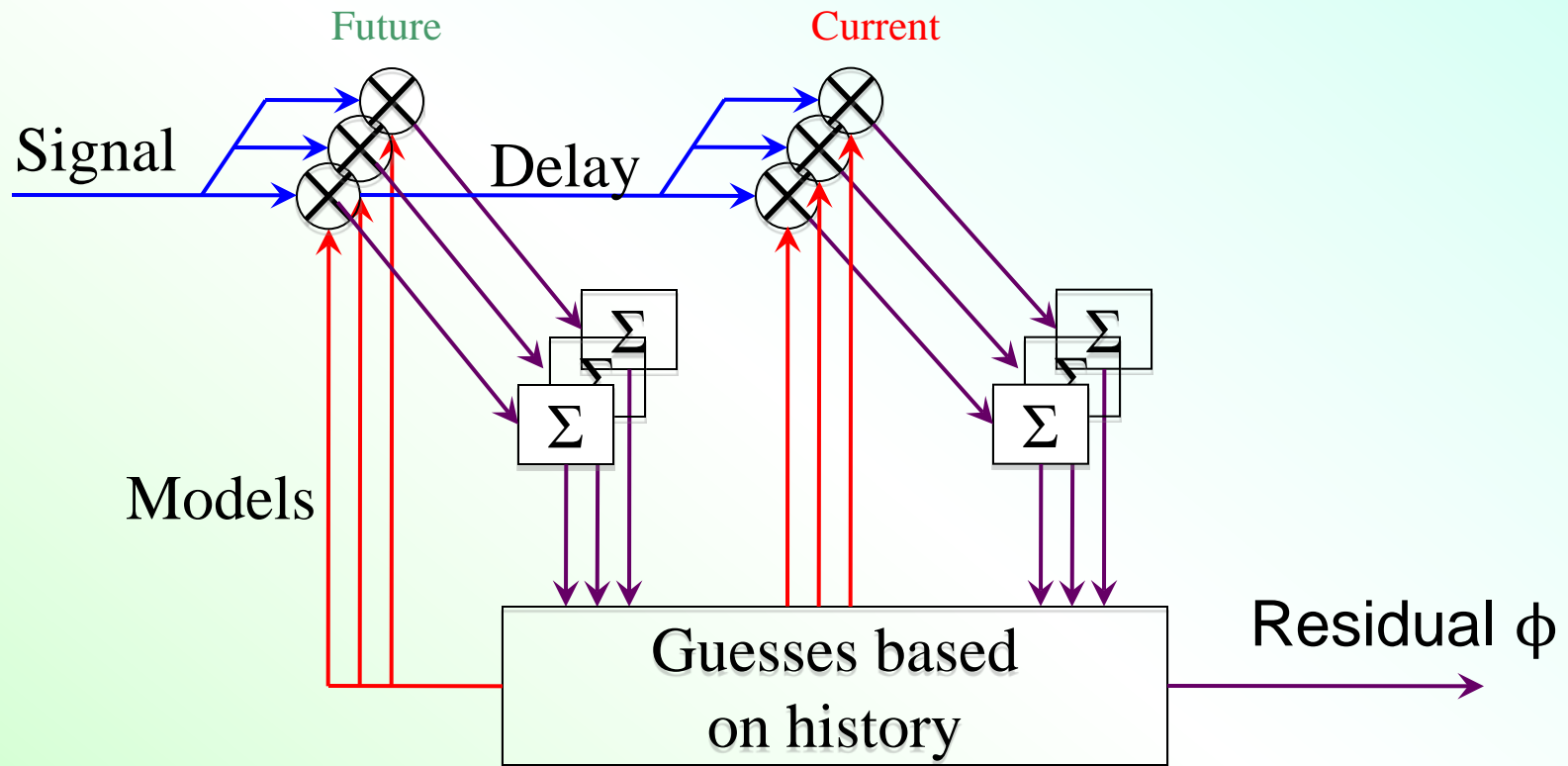
Example 3: Phase-Locked Loops

Try more guesses

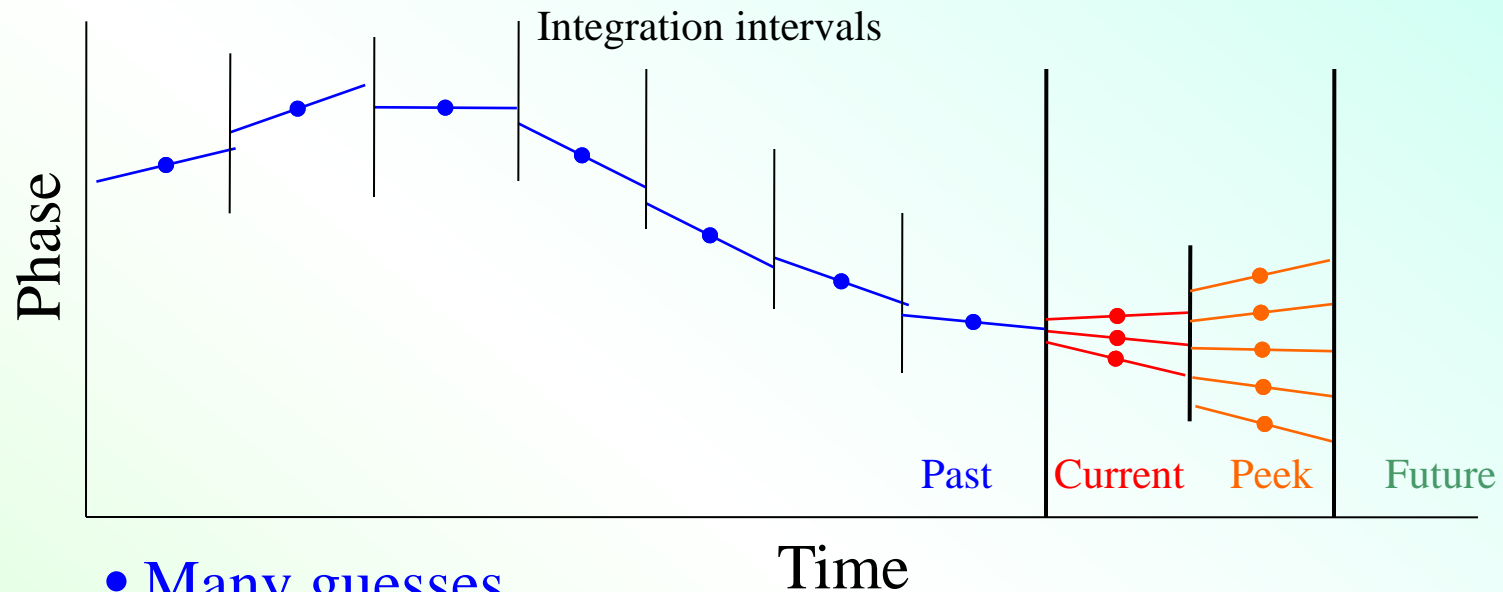


Example 3: Phase-Locked Loops

Look ahead



Example 3: Phase-Locked Loops



- Many guesses
=> Much more likely to get it right
- Have past, current, and future results
=> Symmetrizes time
- More stable, lower SNR threshold
- No Literature / Theory

Summary

Modern Digital Signal Processing

- Hardware capability/cost improving dramatically
- Many DSP ideas with GNSS-R applications
- Presented 3 diverse possibilities
- BOC signals ripe for ideas