

COMPUTATION OF THE YIELD SURFACE OF DOWELLED TIMBER JOINTS BY USING A FEASIBLE DIRECTION METHOD

D. Laplume, T. Descamps

Department of Civil Engineering & Structural Mechanics
Polytechnic Faculty of Mons
Rue du Joncquois, 53 B-7000 Mons, Belgium
e-mail: david.laplume@fpms.ac.be , web page: <http://www.gcms.fpms.ac.be>

Key words: Limit analysis, Yield criterion, Timber, Joint.

Summary. *This article presents recent works in relation with the strength of dowelled timber connections. When numerous dowels are involved, computing the global strength of a joint can be quite tedious. The proposed method consists in using the individual embedment strength of each dowel, computed according to EC5¹, and finding a lower bound of the global strength of the joint by using the static theorem of limit analysis². The resulting optimization problem is solved with a feasible direction method³.*

1 INTRODUCTION

Let us consider two timber members 1 and 2 connected by a set of steel dowels of diameter d . Hence, the joint is in double shear, which means that member 1 is made of twin beams of individual thickness t_1 on each side of member 2 which is a single beam of thickness t_2 .

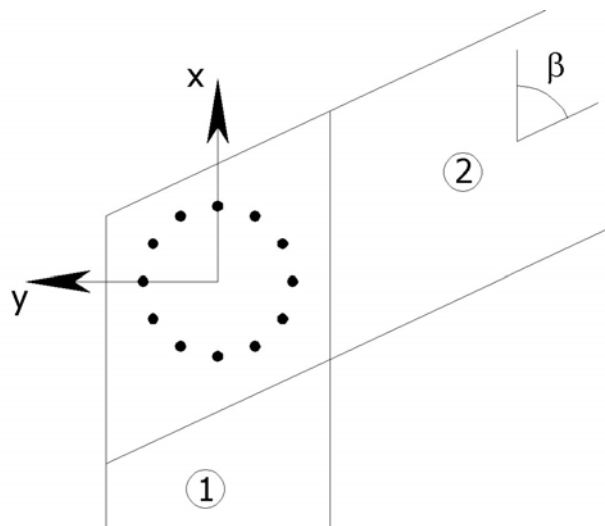


Figure 1: dowelled joint

As shown on figure 1, those members are subjected to several actions: bending moments M_{Sd1} and M_{Sd2} , shear forces V_{Sd1} and V_{Sd2} and normal forces N_{Sd1} and N_{Sd2} . Note that the

magnitudes of these forces are computed for every considered ultimate limit state (ULS) load combination. The aim of the study consists in generating the yield surface of the joint in a 3-dimension space, taking into account the interaction of bending moment, shear force and normal force.

2 NON-DIMENSIONAL FORCES

M_{Rd1} and M_{Rd2} denote the strength of members 1 and 2 in pure bending. N_{Rd1} and N_{Rd2} denote their strength in compression while V_{Rd1} and V_{Rd2} are the respective shear strengths. If the same symbols are used with a * to denote the respective joint strengths, it is convenient to define the following variables:

$$\begin{aligned}\mu_1 &= \frac{M_{Rd1}^*}{M_{Rd1}} & \mu_2 &= \frac{M_{Rd2}^*}{M_{Rd2}} \\ \eta_1 &= \frac{N_{Rd1}^*}{N_{Rd1}} & \eta_2 &= \frac{N_{Rd2}^*}{N_{Rd2}} \\ \nu_1 &= \frac{V_{Rd1}^*}{V_{Rd1}} & \nu_2 &= \frac{V_{Rd2}^*}{V_{Rd2}}\end{aligned}\quad (1)$$

This way, the yield criterion of the joint may be represented as a surface of equation:

$$y(\mu_1, \eta_1, \nu_1) = 0 \quad (2)$$

This surface can be computed point by point, by setting for example:

$$\begin{aligned}\mu_1 &= \theta \eta_1 \\ \nu_1 &= \varphi \eta_1\end{aligned}\quad (3)$$

3 MATHEMATICAL FORMULATION

Let us consider a local coordinate system oxy attached to member 1, and a set of n dowels of index i , each of them located at point (x_i, y_i) and subjected to unknown forces F_{xi} and F_{yi} . In order to find a point of the yield surface of the joint, we have to maximize:

$$\sqrt{\mu_1^2 + \eta_1^2 + \nu_1^2} \quad (4)$$

Two kinds of constraints must be taken into account. First of all, to ensure that the set of forces F_{xi} and F_{yi} is plastically admissible, the force applied at each dowel may not exceed its embedment force F_{Vj} (with $j=1..4$) given by the equations of Johansen used in EC5¹. The resulting constraints are:

$$F_{xi}^2 + F_{yi}^2 \leq F_{Vj}^2 \quad \begin{array}{l} i \in [1, n] \\ j \in [1, 4] \end{array} \quad (5)$$

The set of forces F_{xi} and F_{yi} must also be statically admissible, thus compatible with the forces and moments acting on the members:

$$\begin{aligned} M_{Rd1}^* &= \sum_{i=1}^n (F_{xi}y_i - F_{yi}x_i) \\ N_{Rd1}^* &= \sum_{i=1}^n F_{xi} \\ V_{Rd1}^* &= \sum_{i=1}^n F_{yi} \end{aligned} \quad (6)$$

The forces F_{xi} and F_{yi} are the design variables of the optimization problem. The objective function (4) can be expressed from (6) as a function of those forces. In order to allow the use of a feasible direction method³, constraints (3) must be converted into inequality constraints. If ε denotes a small positive number acting as a tolerance, they become:

$$\begin{aligned} \mu_1 &\geq \theta\eta_1 - \varepsilon & v_1 &\geq \varphi\eta_1 - \varepsilon \\ \mu_1 &\leq \theta\eta_1 + \varepsilon & v_1 &\leq \varphi\eta_1 + \varepsilon \end{aligned} \quad (7)$$

Thus for a n -dowel joint, the optimization problem involves $4n+4$ constraints. For given values of θ and φ , the solution of the problem leads to a point of the yield surface. With this method, the designer has two options:

For each ULS load combination, the corresponding values of θ and φ can easily be computed from the actions M_{Sd1} , N_{Sd1} and V_{Sd1} . The related directions allow to compute one point of the yield surface for each combination. A quick verification of the joint is then possible.

On the other hand, the whole yield surface may be generated, using a point-by-point construction. In this case, the behaviour of the joint can be studied thoroughly.

4 CONCLUSIONS

The implementation of a feasible direction algorithm combined with the static theorem of limit analysis allows a correct assessment of the strength of dowelled timber connections, while the more widely used simplified approach tends to underestimate it.

The computation time for optimization remains reasonable, compared to the obtained gain of accuracy on the joint strength.

A further step should be taken in considering not only the strength of a given joint, but also an optimization of the joint itself under a given set of load combinations.

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